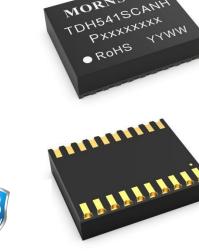
# **MORNSUN**<sup>®</sup>

# TDH541SCANH DFN package isolated CAN transceiver

#### Features

- Ultra-small, ultra-thin, chip scale DFN package
- Compliant with ISO11898-2 standard
- Integrate 5V efficiently power supply
- I/O power supply range supports 3.3V and 5V microprocessors
- High isolation to 5000VDC
- Bus-Pin ESD protection up to 15kV(HBM)
- Baud rate up to 1Mbps
- -40V to +40V bus fault protection
- >25kV/us CMTI
- TXD dominant time-out function
- · Low communication delay
- The bus supports maximum 110 nodes
- Industrial operating ambient temperature range: -40°C to +125℃
- Meet EN62368 standards
- Moisture Sensitivity Level (MSL) 3
- Bottom PCB meets CTI Category II (400≤CTI<600)</li>



Package

#### Applications

- · Industrial automation, control, sensors and drive systems
- · Building and greenhouse environmental control(HVAC) automation
- Security system
- Transport
- Medical treatment
- Telecommunication
- CAN Bus standard such as CAN open, Device Net, NMEA2000, ARNIC825, ISO11783, CAN Kingdom, CAN aerospace

#### **Functional Description**

TDH541SCANH is a isolated CAN Bus transceiver, which is compliant with ISO11898-2 standard. Their logic side supports 3.3V and 5V logic level conversion.TDH541SCANH integrate 5V efficiently power. The TDH541SCANH provide differential transmitting and receiving capability between the CANH protocol controller and the physical layer bus. It is capable of running at data rates of up to 1Mbps. The device has the function of series line, over-voltage(-40V to 40V), ground loss protection and thermal shutdown so that it is especially suitable for working in harsh environment.



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#### Pin Connection

	_			
<b>GND</b> 1	1.		20	GND2
NC	2		19	VISOIN
GND	3		18	S
RXD	4		17	CANH
TXD	5	TDH541SCANH	16	GND2
Vio	6	IDH0415CANH	15	CANL
GND	7		14	NC
Vcc	8		13	GND2
GND	9		12	Visoout
GND	10		11	GND2
	L			

Note: All GND<sub>1</sub> pins are internally connected; All GND<sub>2</sub> pins are internally connected.

#### Function Table

Letter	Description
Н	High-Level
L	Low-Level
X	Unrelated
Z	High Impedance

Inp	outs	Outputs		Bus State	
TXD	S	CANH	CANL	Bus State	
L	L (Or No Connection)	Н	L	Dominant	
H ( Or No Connection )	Х	Z	Z	Recessive	
Х	Н	Z	Z	Recessive	

Table 1. Driver Function table

#### Table 2. Receiver Function table

V <sub>ID</sub> =CANH-CANL	RXD	Bus State
V <sub>ID</sub> ≥0.9V	L	Dominant
0.5< V <sub>ID</sub> <0.9V	Uncertainty	Uncertainty
V <sub>ID</sub> ≤0.5V	Н	Recessive
OPEN	Н	Recessive

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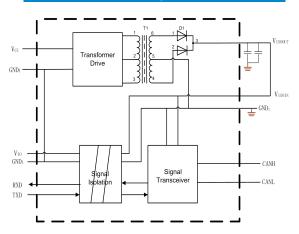
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### Internal Block Diagram



	1	-
Pin Number	Pin Name	Pin Functions
1	GND <sub>1</sub>	Ground(Logic side)
2	NC	No connect
3	GND₁	Ground(Logic side)
4	RXD	Receiver output pin.
5	TXD	Driver input pin
6	V <sub>IO</sub>	Isolation power supply pin. By using 0.1uF ceramic capacitance ground GND1.
7	GND1	Ground(Logic side)
8	Vcc	Power supply pin. By using 1uF ceramic capacitance ground GND1.
9	GND <sub>1</sub>	Ground(Logic side)
10	GND1	Ground(Logic side)
11	GND <sub>2</sub>	Ground (Bus side)
12	VISOOUT	Insulation power output. By using 1uF ceramic capacitance ground GND2. The pin needs to be connected to pin19 in application.
13	GND <sub>2</sub>	Ground (Bus Side)
14	NC	No connect
15	CANL	CANL pin
16	GND <sub>2</sub>	Ground (Bus side)
17	CANH	CANH pin
18	S	Silent control mode input, this pin connect to ground GND2.
19	VISOIN	Insulation power input. By using 0.1uF ceramic capacitance ground2. The pin needs to be connected to pin12 in application.
20	GND <sub>2</sub>	Ground (Bus side)

Absolute Maximum Ratings

General test conditions: Free-air, normal operating temperature range (unless otherwise specified).

Parameters	Unit
Supply voltage, (V <sub>cc</sub> )	-0.3V to +5.6V
Digital input voltage TXD, RXD	-0.3V to +6V
Bus voltage (CANH, CANL)	-40 to 40V
Receiver output current	-15 to 15mA
Operating temperature range	-40°C to +125°C
Storage temperature range	-50°C to +130°C
Reflow soldering temperature	Peak temp. ≤250°C, maximum duration ≤60s at 217°C. Please also refer to IPC/JEDEC J-STD-020D. 3.

Important: Exposure to absolute maximum rated conditions for an extended period may severely affect the device reliability, and stress levels exceeding the "Absolute Maximum Ratings" may result in permanent damage.

#### **Recommended Operating Conditions**

	Paramete	ers	Min.	Nom.	Max.	Unit	
Vcc	Po	wer supply	4.75	5	5.25	V	
VIO	Power su	ipply(Logic Side)	2.75		5.25	V	
VI or VIC	Voltage at any bus	terminal (differential mode)	-40		40	V	
VIH	High-level input voltage(TXD)		2			V	
VIL	Low-level input voltage(TXD)				0.8	V	
	High-level output current     Driver       Receiver     V <sub>CC</sub> =5V	Driver	-70				
Юн		-4			- mA		
		Driver			70		
Iol	Low-level output current	Receiver V <sub>CC</sub> =5V			4	mA	
T <sub>A</sub>	Operating	temperature range	-40		125	°C	
Icc	Recessiv	ve mode current		20	35	mA	

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Icc	Working current	V <sub>CC</sub> = 5V,R <sub>L</sub> = 60Ω;TXD signal: f=500kHz;Duty=50%		35	55	mA
	Siç	gnaling rate	40		1000	kbps

#### Electrical Characteristics

General test conditions and V<sub>CC</sub>=V<sub>IO</sub>= 5V, Ta =  $25^{\circ}$ C (unless otherwise specified).

	Parameters	Conditions	Min.	Nom.	Max.	Unit
Driver		· · · · · ·		•	•	1
N7 1	Dominant CANH output voltage		2.75	3.5	4.5	.,
V <sub>O(D)</sub>	Dominant CANL output voltage	Figure 8 $V_{TXD}$ = 0 V, R <sub>L</sub> = 60 Ω	0.5	1.5	2.25	V
V <sub>O(R)</sub>	Recessive bus voltage	Figure 8 V <sub>TXD</sub> = 2 V, R <sub>L</sub> = 60 Ω	2	2.5	3	V
V <sub>OD(D)</sub>	Differential output voltage	Figure 8 $V_{TXD}$ = 0 V, t < $t_{to(dom)TXD}$ , V <sub>CC</sub> =4.75 V to 5.25 V, R <sub>L</sub> = 50 to 65 $\Omega$	1.5		3	V
M		Figure 8 $V_{TXD}$ = 5 V, R <sub>L</sub> = 60 $\Omega$	-0.12		0.012	v
V <sub>OD(R)</sub>	Recessive differential output voltage	V <sub>TXD</sub> = 5 V, No load	-0.5		0.05	
l <sub>iH</sub>	TXD High-level input current	V <sub>TXD</sub> =2 V	2			mA
l <sub>IL</sub>	TXD Low-level input current	V <sub>TXD</sub> =0.8 V	2			mA
R <sub>TXD</sub>	Internal TXD Pull up Resistor			9.1		kΩ
Receiver						
V <sub>IT+</sub>	Positive-going input threshold voltage			750	900	mV
V <sub>IT-</sub>	Negative-going input threshold voltage	Figure 11	500	650		mV
V <sub>hys</sub>	Hysteresis voltage (V <sub>IT+</sub> - V <sub>IT-</sub> )			120		mV
M	High-level output voltage	I <sub>OH</sub> = –4 mA, Figure 9	$V_{10} - 0.4$	V <sub>IO</sub> – 0.2		v
V <sub>он</sub>	High-level output voitage	$I_{OH}$ = -20 uA, Figure 9	$V_{10} - 0.4$	V <sub>IO</sub> – 0.2		v
Voi	Low-level output voltage	$I_{OL}$ = 4 mA, Figure 9		0.2	0.4	v
VOL	Low-level output voltage	$I_{OL}$ = 20 uA, Figure 9		0.2	0.4	v
Cı	Input capacitance to ground (CANH or CANL)	$V_{TXD}$ = 5 V, VI = 0.4 sin (4E6 $\pi$ t) + 2.5 V		13		pF
CID	Differential input capacitance	$V_{TXD}$ = 5 V, $V_1$ = 0.4 sin (4E6 $\pi$ t)		5		pF
R <sub>ID</sub>	Differential input resistance	$V_{TXD}$ = 5 V	15	30	40	kΩ
R <sub>IN</sub>	Input resistance (CANH or CANL)	V <sub>TXD</sub> = 5 V	30		80	kΩ
R I(m)	Input resistance matching: [1 - R <sub>IN(CANH)</sub> / R <sub>IN(CANL)</sub> ] × 100%	$V_{CANH} = V_{CANL}$	-3%	0%	3%	
ESD	НВМ	CANH, CANL pin to GND			±15	kV
ESD	ПВМ	Other pins			±2	kV
EFT	IEC61000-4-4 : Perf. Criteria B	CANH, CANL and GND			±2	kV
Surge	IEC61000-4-5 : Perf. Criteria B	CANH, CANL and GND(Common Mode)			±2	kV
	Isolation voltage				5000	VDC
Insulation characteristics	Insulation resistance		1000			MΩ
010100101101103	Isolation capacitor			3		pF
CMTI	Common Mode Transient Immunity	$V_{TXD} = V_{CC}$ or 0 V, $V_{CM} = 1$ kV, transient magnitude = 800 V	25			kV/us

#### Transmission Characteristics General test conditions and $V_{CC}=V_{IO}=5V$ , Ta = 25°C (unless otherwise specified).

	Parameters	Conditions	Min.	Nom.	Max.	Unit
tonTxD	Propagation delay TXD On to bus active		80	150	ns	
t <sub>offTxD</sub>	Propagation delay TXD Off to bus inactive	R <sub>L</sub> = 60 Ω, C <sub>L</sub> = 100 pF, see Figure 10		80	200	ns
tonRxD	Propagation delay RXD On to receiver active	and Figure 12		60	300	ns
t <sub>offRxD</sub>	Propagation delay RXD Off to receiver inactive			60	250	ns
t <sub>тхD_</sub> dto	Dominant time-out time	C <sub>L</sub> =100 pF	1.2		3.8	ms

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Parameters	Value	Unit
Weight	0.9(Тур.)	g

Typical Performance Curves

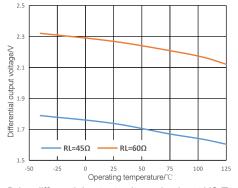


Figure 1. Drive differential output voltage dominant VS Temperature

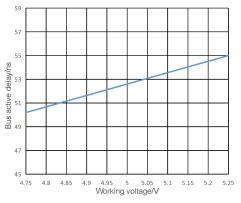


Figure 3. Propagation delay from TXD On to bus active VS Working voltage

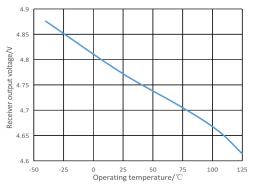


Figure 5. Receiver output voltage VS Temperature

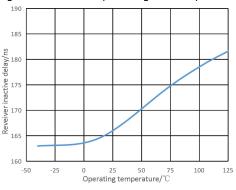


Figure 7. Receiver inactive delay VS Operating Temperature

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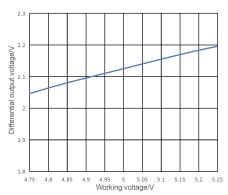


Figure 2. Drive differential output voltage dominant VS Working voltage

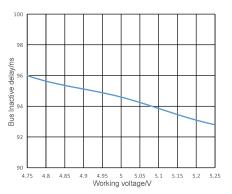


Figure 4. Propagation delay from TXD Off to bus inactive VS Working voltage

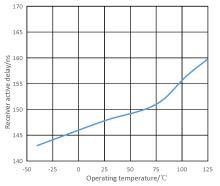
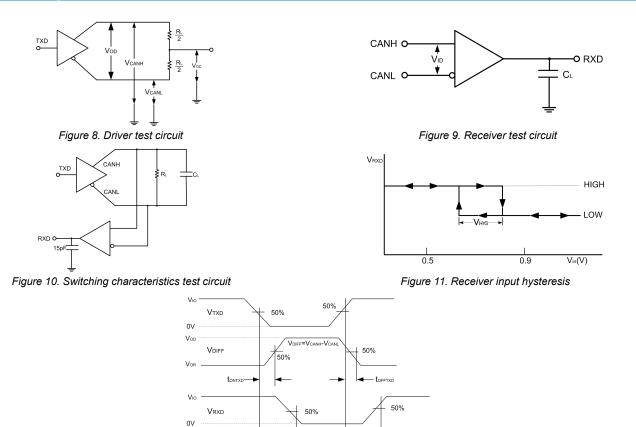


Figure 6. Receiver active delay VS Operating Temperature

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toffra

supply voltages. The power dissipation increases when a short circuit occurs. The short-circuit protection function protects the driver stage from damage. Over-temperature protection: TDH541SCANH has over-temperature protection. When the junction temperature exceeds 160°C, the current in the driver stage will decrease. Because the drive tube is the primary energy consuming component, current reduction can reduce power consumption and reduce chip temperature. At the same time, the rest of the chip remains functional.

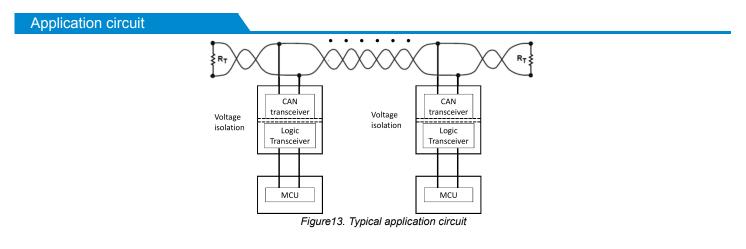
controller, it the inner integration insulate DC/DC power supply. which is compliant with ISO11898-2 standard.

Figure 12. Drive and receiver propagation delay

TDH541SCANH is a CAN of a style of separation transceiver with the ability of differential signal transmission between the bus and CAN protocol

Short-circuit protection: TDH541SCANH has current-limiting protection to prevent the drive circuit from short-circuiting to positive and negative

Dominant time-out function: TDH541SCANH has dominant time-out function to prevent if the pin TXD is forced to a permanent low level due to a hardware or software application failure, the built-in TXD dominant timeout timer circuit prevents the bus line from being driven to a permanent dominant state (blocking all network traffic). The timer is triggered by the negative edge on pin TXD, If the low level on pin TXD lasts longer than the internal timer value ( $t_{TXD}$  <sub>DTO</sub>), the transmitter will be disabled and the drive bus will enter a recessive state. The timer is reset by the positive edge on pin TXD.



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**Detailed Description** 

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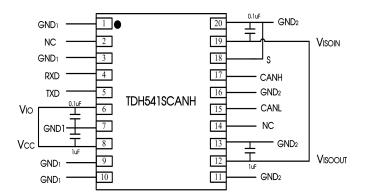


Figure 14. Typical Application of PCB layout

In General, Vcc and VIo can be shorted(Figure 14) .If the controller doesn't support 5V signal input, it can power 3.3V for VIo. When the module works in normal condition connect the S foot to GND2.

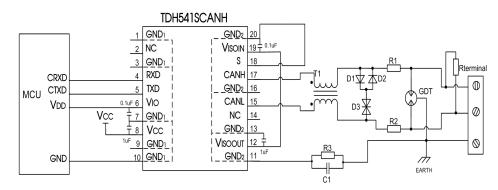


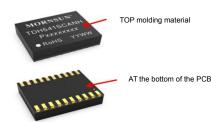
Figure 15. Port protection circuit for harsh environments

Recommended components and values:

Component	Recommended part, value	Component	Recommended part, value		
R3	1ΜΩ	D1、D2	1N4007		
C1	1nF, 2kV	D3	SMBJ30CA		
T1	ACM2520-301-2P	Rterminal	<b>120</b> Ω		
GDT	B3D090L	R1、R2	2.7Ω/2W		

When the module is used in applications with harsh environment, it can be susceptible to large energy like lightning strike, etc. in which case, it is essential to add an adequate protection circuit to the CAN signal ports to protect the system from failure and maintain a reliable bus communication. Figure 15 provides a recommended protection circuit design for high-energy lightning surges, with a degree of protection related to the selected protection device. Parameter description lists a set of recommended circuit parameters, which can be adjusted according to the actual application situation. Also, when using the shielded cable, the reliable single-point grounding of the shield must be achieved.

Note: The recommended components and values is a general guideline only and must be verified for the actual user's application. We recommended using PTC's for R1 and R2 and to use fast recovery diodes for D1 and D2.



The top molding material of the product meets CTI category I (600≤CTI); Bottom PCB plate meets CTI category I I (400≤CTI<600).



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#### **Using Suggests**

Power isolation V<sub>ISOOUT</sub> need through a series of capacitors connected to the output pin V<sub>ISOIN</sub>, the power supply is not recommended for other purposes, otherwise it may cause the bus voltage did not meet the requirements of communication, causes the communication failure.
Hot-swap is not supported.

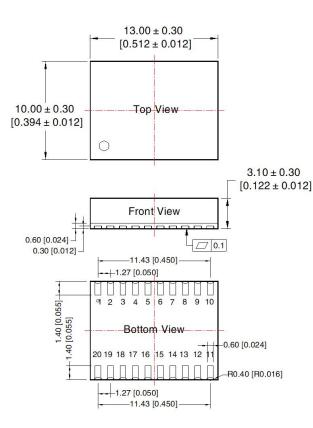
③ If the external input of TXD is insufficient, the pull-up resistor should be added according to the situation.

④ Refer to IPC 7093 for the welding process design of this product. For detailed operation guidance, please refer to Hot Air Gun Welding Operation Instruction for DFN Package Product or Welding Operation Instruction for DFN Package Product.

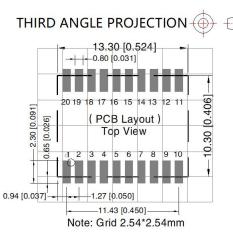
#### Ordering Information

Pa	rt number	Package	Number of pins	Product marking	Tape & Reel		
TDH	TDH541SCANH DFN		20	TDH541SCANH	300/REEL		

#### Package Information



Note: Unit: mm[inch] Pin diameter tolerances: ± 0.10[±0.004]

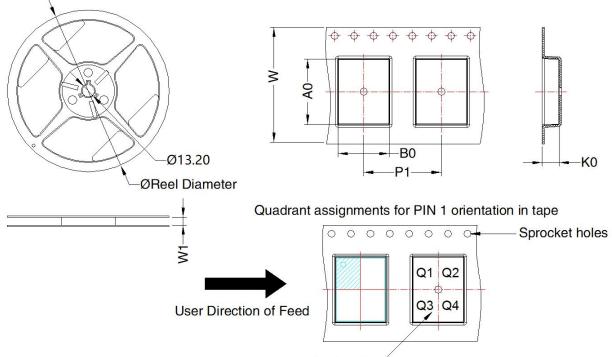


Pin-Out Pin Mark Pin Mark GND1 GND<sub>2</sub> 1 11 2 NC 12 VISOOUT GND1 GND<sub>2</sub> 3 13 RXD NC 4 14 5 TXD 15 CANL 6 Vio 16 GND<sub>2</sub> 7 CANH GND1 17 8 Vcc 18 S 9 GND1 19 VISOIN GND1 GND<sub>2</sub> 10 20

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#### **Pocket Quadrants**

Device	Package Type	Pin	MPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TDH541SCANH	DFN 10x13	20	300	180.0	24.4	13.52	10.52	3.5	16.0	24.0	Q1

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