

## TD541SCANH-S DFN package isolated CAN transceiver

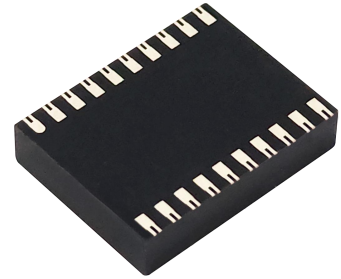
### Features

- Ultra-small, ultra-thin, chip scale DFN package
- Compliant with ISO11898-2 standard
- Integrate 5V efficiently power supply
- I/O power supply range supports 3.3V and 5V microprocessors
- High isolation to 5000VDC
- Bus-Pin ESD protection up to 15kV(HBM)
- Baud rate up to 1Mbps
- -40V to +40V bus fault protection
- >25kV/us CMTI
- TXD dominant time-out function
- Low communication delay
- The bus supports maximum 110 nodes
- Industrial operating ambient temperature range: -40°C to +125°C
- AEC-Q100 experiment in progress
- EN62368 approval
- Moisture Sensitivity Level (MSL) 3
- Bottom PCB meets CTI Category II ( $400 \leq CTI < 600$ )

### Applications

- Industrial automation, control, sensors and drive systems
- Building and greenhouse environmental control(HVAC) automation
- Security system
- Transport
- Medical treatment
- Telecommunication
- CAN Bus standard such as CAN open, Device Net, NMEA2000, ARNIC825, ISO11783, CAN Kingdom, CAN aerospace

### Package



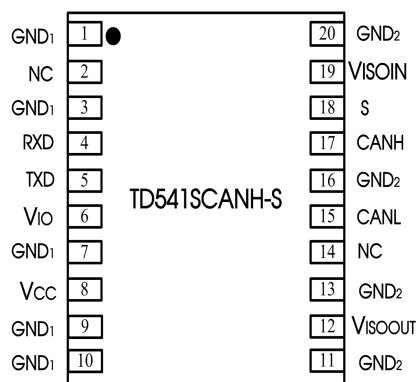
### Functional Description

TD541SCANH-S is a isolated CAN Bus transceiver, which is compliant with ISO11898-2 standard. Their logic side supports 3.3V and 5V logic level conversion. TD541SCANH-S integrate 5 V efficiently power. The TD541SCANH-S provide differential transmitting and receiving capability between the CANH protocol controller and the physical layer bus. It is capable of running at data rates of up to 1 Mbps. The device has the function of series line, over-voltage(-40V to 40V), ground loss protection and thermal shutdown so that it is especially suitable for working in harsh environment.

## Contents

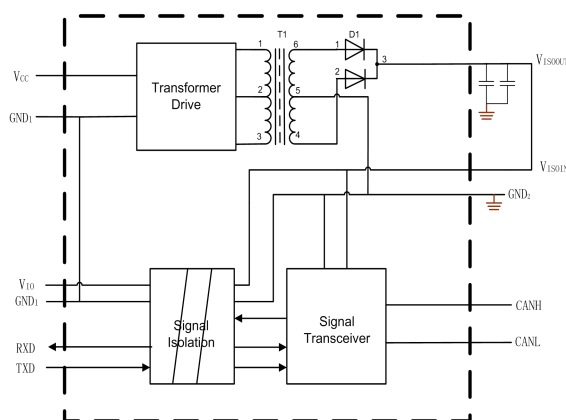
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### Pin Connection



Note: All GND<sub>1</sub> pins are internally connected;  
All GND<sub>2</sub> pins are internally connected.

### Internal Block Diagram



### Function Table

| Letter | Description    |
|--------|----------------|
| H      | High-Level     |
| L      | Low-Level      |
| X      | Unrelated      |
| Z      | High Impedance |

Table 1. Driver Function table

| Inputs                 |                        | Outputs |      | Bus State |
|------------------------|------------------------|---------|------|-----------|
| TXD                    | S                      | CANH    | CANL |           |
| L                      | L ( Or No Connection ) | H       | L    | Dominant  |
| H ( Or No Connection ) | X                      | Z       | Z    | Recessive |
| X                      | H                      | Z       | Z    | Recessive |

Table 2. Receiver Function table

| V <sub>ID</sub> =CANH-CANL   | RXD         | Bus State   |
|------------------------------|-------------|-------------|
| V <sub>ID</sub> ≥0.9V        | L           | Dominant    |
| 0.5 < V <sub>ID</sub> < 0.9V | Uncertainty | Uncertainty |
| V <sub>ID</sub> ≤0.5V        | H           | Recessive   |
| OPEN                         | H           | Recessive   |

### Pin Descriptions

| Pin Number | Pin Name            | Pin Functions  |
|------------|---------------------|--|
| 1          | GND <sub>1</sub>    | Ground(Logic side)   |
| 2          | NC                  | No connect   |
| 3          | GND <sub>1</sub>    | Ground(Logic side)   |
| 4          | RXD                 | Receiver output pin  |
| 5          | TXD                 | Driver input pin   |
| 6          | V <sub>IO</sub>     | Isolation power supply pin. By using 0.1uF ceramic capacitance ground GND <sub>1</sub>   |
| 7          | GND <sub>1</sub>    | Ground(Logic side)   |
| 8          | V <sub>CC</sub>     | Power supply pin. By using 1uF ceramic capacitance ground GND <sub>1</sub>   |
| 9          | GND <sub>1</sub>    | Ground(Logic side)   |
| 10         | GND <sub>1</sub>    | Ground(Logic side)   |
| 11         | GND <sub>2</sub>    | Ground (Bus side)  |
| 12         | V <sub>ISOOUT</sub> | Insulation power output. By using 1uF ceramic capacitance ground GND <sub>2</sub> . The pin needs to be connected to pin19 in application  |
| 13         | GND <sub>2</sub>    | Ground (Bus Side)  |
| 14         | NC                  | No connect   |
| 15         | CANL                | Low level CAN voltage input/output   |
| 16         | GND <sub>2</sub>    | Ground (Bus side)  |
| 17         | CANH                | High level CAN voltage input/output  |
| 18         | S                   | Ground Pin. In normal applied, this pin no connect or connect to ground GND <sub>2</sub>   |
| 19         | V <sub>ISOIN</sub>  | Insulation power input. By using 0.1uF ceramic capacitance ground GND <sub>2</sub> . The pin needs to be connected to pin12 in application |
| 20         | GND <sub>2</sub>    | Ground (Bus side)  |

## Absolute Maximum Ratings

General test conditions: Free-air, normal operating temperature range (unless otherwise specified).

| Parameters                       | Unit   |
|----------------------------------|--|
| Supply voltage, V <sub>CC</sub>  | -0.3V to +5.6V   |
| Digital input voltage (TXD, RXD) | -0.3V to +6V   |
| Bus voltage (CANH, CANL)         | -40 to 40V   |
| Receiver output current          | -15 to 15mA  |
| Operating temperature range      | -40°C to +125°C  |
| Storage temperature range        | -50°C to +125°C  |
| Reflow soldering temperature     | Peak temp. ≤250°C, maximum duration ≤60s at 217°C. Please also refer to IPC/JEDEC J-STD-020D. 3. |

Important: Exposure to absolute maximum rated conditions for an extended period may severely affect the device reliability, and stress levels exceeding the "Absolute Maximum Ratings" may result in permanent damage.

## Recommended Operating Conditions

| Parameters                        |   | Min. | Nom. | Max. | Unit |
|-----------------------------------|---|------|------|------|------|
| V <sub>CC</sub>                   | Power supply                                    | 4.5  | 5    | 5.5  | V    |
| V <sub>IO</sub>                   | Power supply(Logic Side)                        | 2.75 |      | 5.25 | V    |
| V <sub>I</sub> or V <sub>IC</sub> | Voltage at any bus terminal (differential mode) | -40  |      | 40   | V    |
| V <sub>IH</sub>                   | High-level input voltage(TXD)                   | 2    |      | 5.5  | V    |
| V <sub>IL</sub>                   | Low-level input voltage(TXD)                    | 0    |      | 0.8  | V    |
| T <sub>A</sub>                    | Operating temperature range                     | -40  |      | 125  | °C   |
| I <sub>CC</sub>                   | Recessive mode current                          |      | 20   | 35   | mA   |
| I <sub>CC</sub>                   | Working current                                 |      | 35   | 55   | mA   |
|                                   | Signaling rate                                  | 40   |      | 1000 | kbps |

## Electrical Characteristics

General test conditions and V<sub>CC</sub>=V<sub>IO</sub>= 5V, T<sub>a</sub> = 25°C (unless otherwise specified).

| Parameters         |   | Conditions  | Min.                  | Nom.                  | Max.  | Unit  |
|--------------------|---|---|-----------------------|-----------------------|-------|-------|
| <b>Driver</b>      |   |   |                       |                       |       |       |
| V <sub>OD</sub>    | Dominant CANH output voltage  | Figure 8 V <sub>TXD</sub> = 0 V, R <sub>L</sub> = 60 Ω  | 2.75                  | 3.5                   | 4.5   | V     |
|                    | Dominant CANL output voltage  |   | 0.5                   | 1.5                   | 2.25  |       |
| V <sub>OD(R)</sub> | Recessive bus voltage   | Figure 8 V <sub>TXD</sub> = 2 V, R <sub>L</sub> = 60 Ω  | 2                     | 2.5                   | 3     | V     |
| V <sub>OD(D)</sub> | Dominant differential output voltage  | Figure 8 V <sub>TXD</sub> = 0 V, t < t <sub>to(dom)TXD</sub> , V <sub>CC</sub> =4.75 V to 5.25 V, R <sub>L</sub> = 50 to 65 Ω | 1.5                   |                       | 3     | V     |
| V <sub>OD(R)</sub> | Recessive differential output voltage   | Figure 8 V <sub>TXD</sub> = 5 V, R <sub>L</sub> = 60 Ω  | -0.12                 |                       | 0.012 | V     |
|                    |   | V <sub>TXD</sub> = 5 V, No load   | -0.5                  |                       | 0.05  |       |
| I <sub>IH</sub>    | TXD High-level input current  | V <sub>TXD</sub> = 2 V  | 2                     |                       |       | mA    |
| I <sub>IL</sub>    | TXD Low-level input current   | V <sub>TXD</sub> = 0.8 V  | 2                     |                       |       | mA    |
| R <sub>TXD</sub>   | Internal TXD Pull up Resistor   |   |                       | 9.1                   |       | kΩ    |
| <b>Receiver</b>    |   |   |                       |                       |       |       |
| V <sub>IT+</sub>   | Positive-going input threshold voltage  | Figure 11   |                       | 750                   | 900   | mV    |
| V <sub>IT-</sub>   | Negative-going input threshold voltage  |   | 500                   | 650                   |       | mV    |
| V <sub>hys</sub>   | Hysteresis voltage (V <sub>IT+</sub> - V <sub>IT-</sub> )                                 |   |                       | 120                   |       | mV    |
| V <sub>OH</sub>    | High-level output voltage   | I <sub>OH</sub> = -4 mA, Figure 9   | V <sub>IO</sub> - 0.4 | V <sub>IO</sub> - 0.2 |       | V     |
|                    |   | I <sub>OH</sub> = -20 uA, Figure 9  | V <sub>IO</sub> - 0.4 | V <sub>IO</sub> - 0.2 |       |       |
| V <sub>OL</sub>    | Low-level output voltage  | I <sub>OL</sub> = 4 mA, Figure 9  |                       | 0.2                   | 0.4   | V     |
|                    |   | I <sub>OL</sub> = 20 uA, Figure 9   |                       | 0.2                   | 0.4   |       |
| C <sub>I</sub>     | Input capacitance to ground (CANH or CANL)  | V <sub>TXD</sub> = 5 V, V <sub>I</sub> = 0.4 sin(4E6 π t) + 2.5 V   |                       | 13                    |       | pF    |
| C <sub>ID</sub>    | Differential input capacitance  | V <sub>TXD</sub> = 5 V, V <sub>I</sub> = 0.4 sin(4E6 π t)   |                       | 5                     |       | pF    |
| R <sub>ID</sub>    | Differential input resistance   | V <sub>TXD</sub> = 5 V  | 15                    | 30                    | 40    | kΩ    |
| R <sub>IN</sub>    | Input resistance (CANH or CANL)   | V <sub>TXD</sub> = 5 V  | 10                    |                       | 100   | kΩ    |
| R <sub>I(m)</sub>  | Input resistance matching:<br>[1 - R <sub>IN(CANH)</sub> / R <sub>IN(CANL)</sub> ] × 100% | V <sub>CANH</sub> = V <sub>CANL</sub>   | -3%                   | 0%                    | 3%    |       |
| CE                 | CISPR32/EN55032   | Figure 15   | CLASS B               |                       |       |       |
| RE                 | CISPR32/EN55032   | Figure 15   | CLASS A               |                       |       |       |
| ESD                | HBM   | CANH, CANL pin to GND   |                       |                       | ±15   | kV    |
|                    |   | Other pins  |                       |                       | ±2    | kV    |
|                    | Contact   | CANH, CANL pin to GND   |                       |                       | ±2    | kV    |
| EFT                | IEC61000-4-4: Perf. Criteria B  | CANH, CANL and GND  |                       |                       | ±2    | kV    |
| Surge              | IEC61000-4-5: Perf. Criteria B  | CANH, CANL and GND(Common Mode)   |                       |                       | ±2    | kV    |
|                    | Isolation voltage   | TD541SCANH-S  |                       |                       | 5000  | VDC   |
|                    | Insulation resistance   |   | 1000                  |                       |       | MΩ    |
|                    | Isolation capacitor   |   |                       | 3                     |       | pF    |
| CMTI               | Common Mode Transient Immunity  | V <sub>TXD</sub> = V <sub>CC</sub> or 0 V, V <sub>CM</sub> = 1 kV, transient magnitude = 800 V                                | 25                    |                       |       | kV/us |

| Parameters     |  | Conditions   | Min. | Nom. | Max. | Unit |
|----------------|--|--|------|------|------|------|
| $t_{onTXD}$    | Propagation delay TXD On to bus active         | $R_L = 60 \Omega$ , $C_L = 100 \text{ pF}$ , see Figure 10 and Figure 12 |      | 80   | 150  | ns   |
| $t_{offTXD}$   | Propagation delay TXD Off to bus inactive      |  |      | 80   | 200  | ns   |
| $t_{onRXD}$    | Propagation delay RXD On to receiver active    |  |      | 60   | 300  | ns   |
| $t_{offRXD}$   | Propagation delay RXD Off to receiver inactive |  |      | 60   | 250  | ns   |
| $t_{TXD\_DTO}$ | Dominant time-out time                         | $C_L=100 \text{ pF}$   | 0.3  |      | 12   | ms   |

## Physical Specifications

| Parameters | Value     | Unit |
|------------|-----------|------|
| Weight     | 0.8(Typ.) | g    |

## Typical Performance Curves

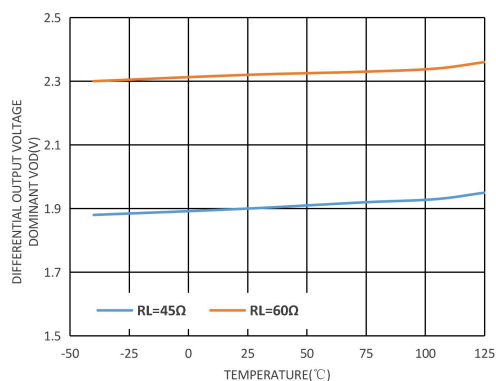


Figure 1. Drive differential output voltage dominant VS Temperature

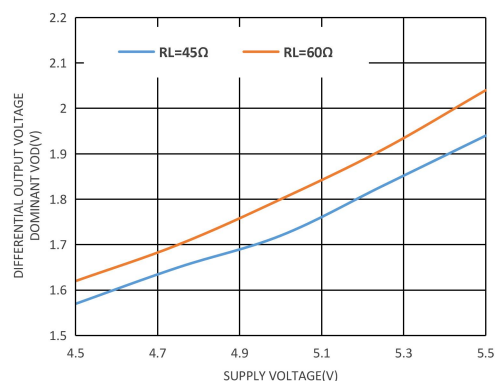


Figure 2. Drive differential output voltage dominant VS Working voltage

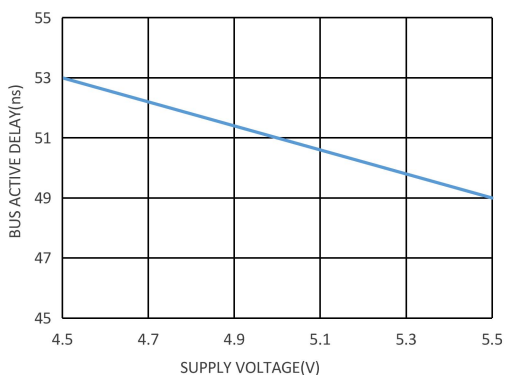


Figure 3. Propagation delay from TXD On to bus active VS Working voltage

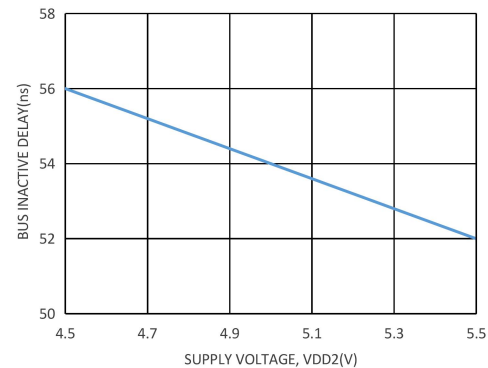


Figure 4. Propagation delay from TXD Off to bus inactive VS Working voltage

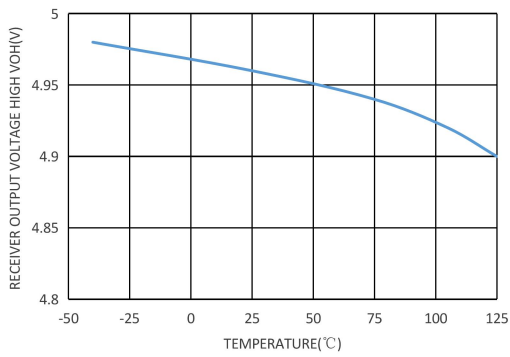


Figure 5. Receiver output voltage VS Temperature

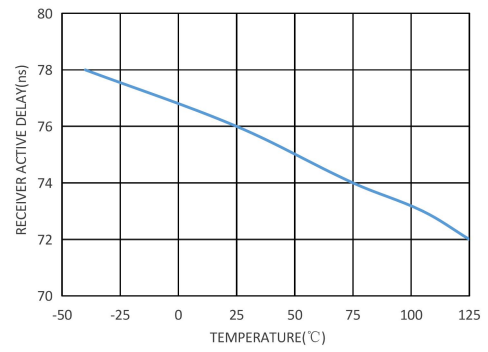


Figure 6. Receiver active delay VS Operating Temperature

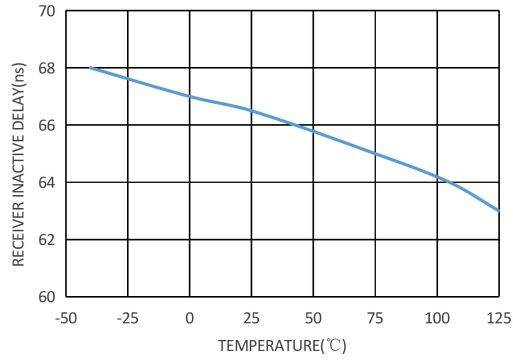


Figure 7. Receiver inactive delay VS Operating Temperature

## Test Circuits

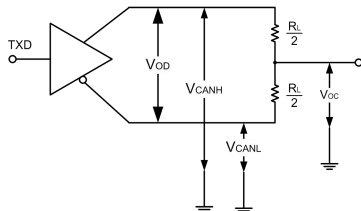


Figure 8. Driver test circuit

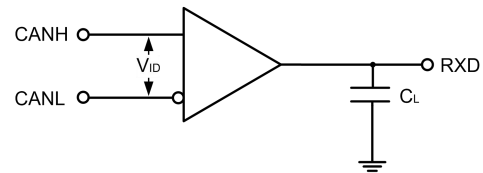


Figure 9. Receiver test circuit

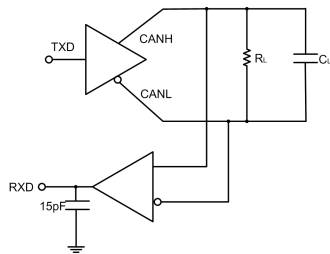


Figure 10. Switching characteristics test circuit

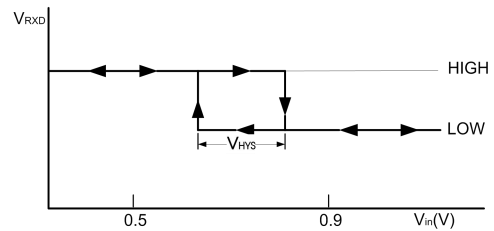


Figure 11. Receiver input hysteresis

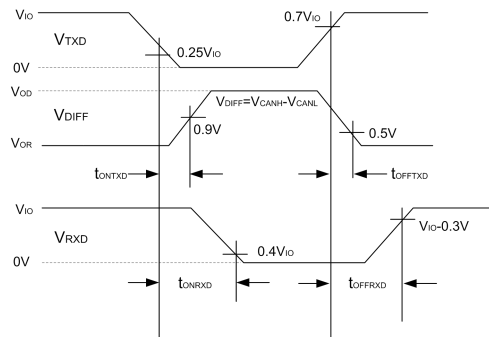


Figure 12. Drive and receiver propagation delay

## Detailed Description

TD541SCANH-S is a CAN of a style of separation transceiver with the ability of differential signal transmission between the bus and CAN protocol controller, it the inner integration insulate DC/DC power supply. which is compliant with ISO11898-2 standard.

**Short-circuit protection:** TD541SCANH-S has current-limiting protection to prevent the drive circuit from short-circuiting to positive and negative supply voltages. The power dissipation increases when a short circuit occurs. The short-circuit protection function protects the driver stage from damage.

**Over-temperature protection:** TD541SCANH-S has over-temperature protection. When the junction temperature exceeds 160°C, the current in the driver stage will decrease. Because the drive tube is the primary energy consuming component, current reduction can reduce power consumption and reduce chip temperature. At the same time, the rest of the chip remains functional.

**Dominant time-out function:** TD541SCANH-S has dominant time-out function to prevent if the pin TXD is forced to a permanent low level due to a hardware or software application failure, the built-in TXD dominant timeout timer circuit prevents the bus line from being driven to a permanent dominant state (blocking all network traffic). The timer is triggered by the negative edge on pin TXD.

If the low level on pin TXD lasts longer than the internal timer value ( $t_{TXD\_DTO}$ ), the transmitter will be disabled and the drive bus will enter a recessive state. The timer is reset by the positive edge on pin TXD.

## Application circuit

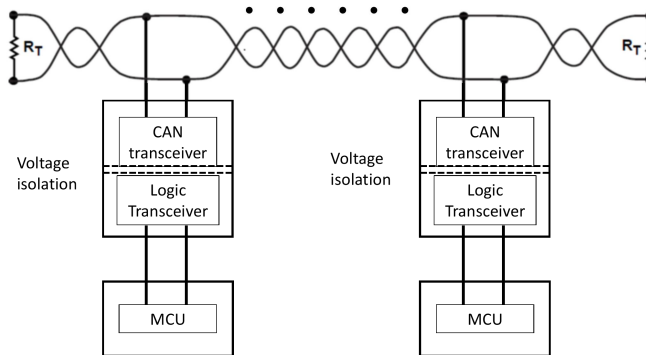


Figure13. Typical application circuit

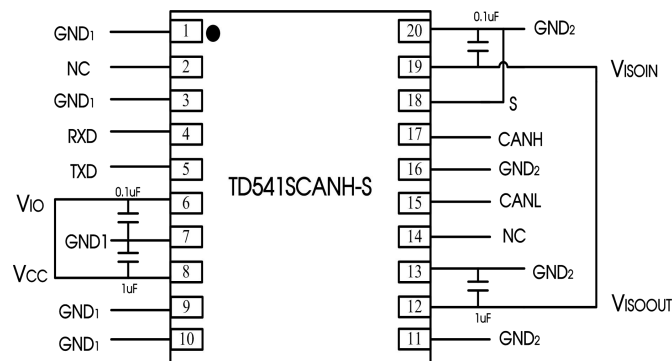


Figure14. Type PCB layout

In General, Vcc and VIo can be shorted(Figure 14) .If the controller doesn't support 5V signal input, it can power 3.3V for VIo. When the module works in normal condition connect the S foot to GND1.

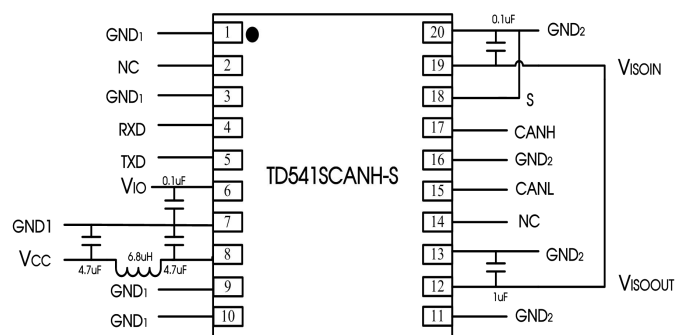


Figure15. EMI Recommended circuit



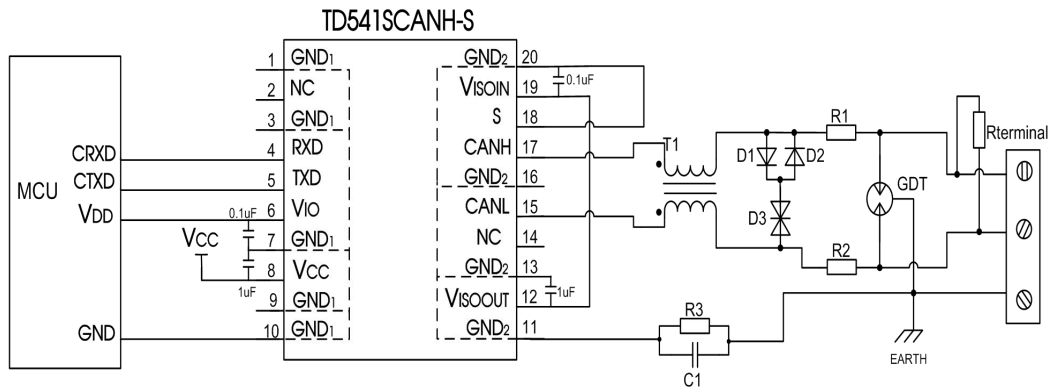


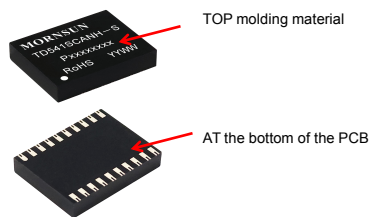
Figure 16. Port protection circuit for harsh environments

Recommended components and values:

| Component | Recommended part, value | Component             | Recommended part, value |
|-----------|-------------------------|-----------------------|-------------------------|
| R3        | 1M $\Omega$             | D1, D2                | 1N4007                  |
| C1        | 1nF, 2kV                | D3                    | SMBJ30CA                |
| T1        | ACM2520-301-2P          | R <sub>terminal</sub> | 120 $\Omega$            |
| GDT       | B3D090L                 | R1, R2                | 2.7 $\Omega$ /2W        |

When the module is used in applications with harsh environment, it can be susceptible to large energy like lightning strike, etc. in which case, it is essential to add an adequate protection circuit to the CAN signal ports to protect the system from failure and maintain a reliable bus communication. Figure 16 provides a recommended protection circuit design for high-energy lightning surges, with a degree of protection related to the selected protection device. Parameter description lists a set of recommended circuit parameters, which can be adjusted according to the actual application situation. Also, when using the shielded cable, the reliable single-point grounding of the shield must be achieved.

Note: The recommended components and values is a general guideline only and must be verified for the actual user's application. We recommended using PTC's for R1 and R2 and to use fast recovery diodes for D1 and D2.



The top molding material of the product meets CTI category I (600 $\leq$ CTI); Bottom PCB plate meets CTI category II (400 $\leq$ CTI<600).

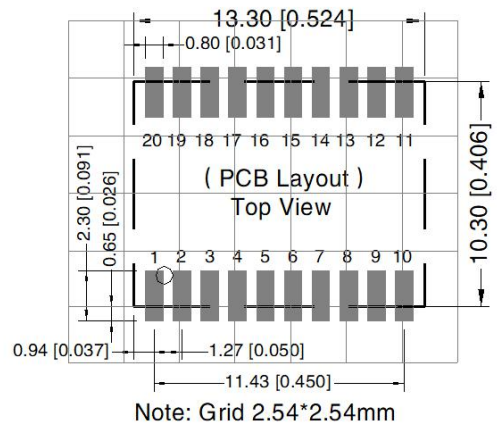
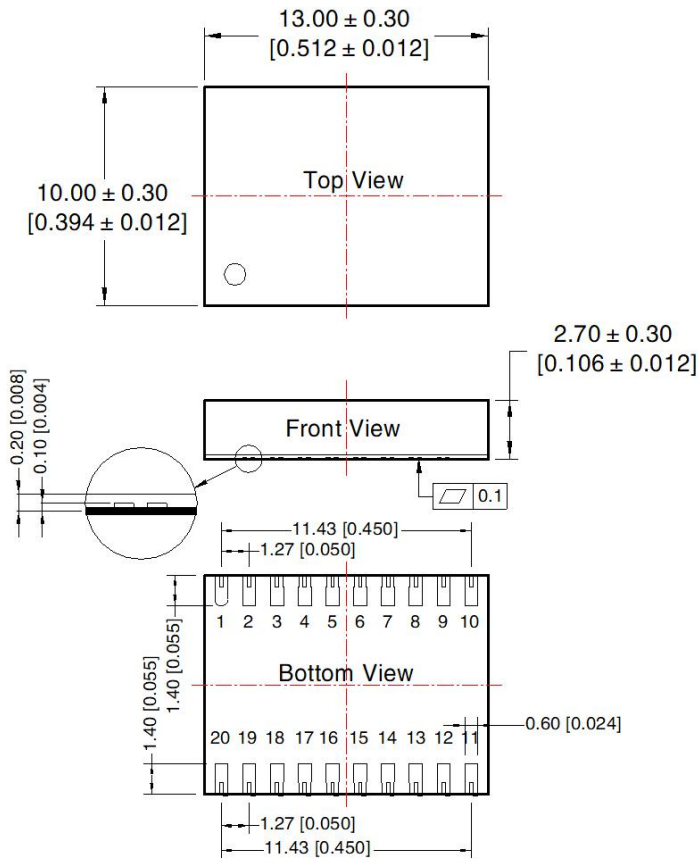
## Using Suggests

- ① Power isolation  $V_{ISOOUT}$  need through a series of capacitors connected to the output pin  $V_{ISOIN}$ , the power supply is not recommended for other purposes, otherwise it may cause the bus voltage did not meet the requirements of communication, causes the communication failure.
- ② Hot-swap is not supported.
- ③ If the external input of TXD is insufficient, the pull-up resistor should be added according to the situation.
- ④ Refer to IPC 7093 for the welding process design of this product. For detailed operation guidance, please refer to *Hot Air Gun Welding Operation Instruction for DFN Package Product* or *Welding Operation Instruction for DFN Package Product*.

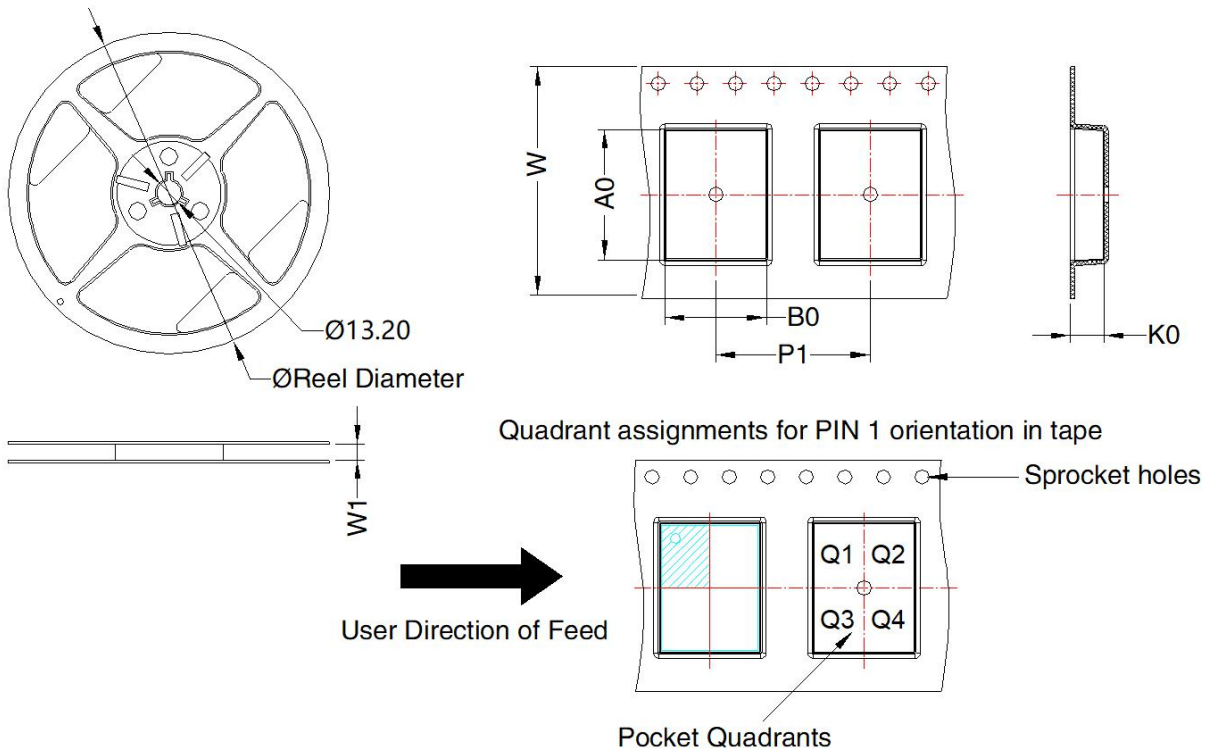
## Ordering Information

| Part number  | Package | Number of pins | Product marking | Tape & Reel |
|--------------|---------|----------------|-----------------|-------------|
| TD541SCANH-S | DFN     | 20             | TD541SCANH-S    | 300/REEL    |





| Pin-Out |                  |     |                     |
|---------|------------------|-----|---------------------|
| Pin     | Mark             | Pin | Mark                |
| 1       | GND <sub>1</sub> | 11  | GND <sub>2</sub>    |
| 2       | NC               | 12  | V <sub>ISOOUT</sub> |
| 3       | GND <sub>1</sub> | 13  | GND <sub>2</sub>    |
| 4       | RXD              | 14  | NC                  |
| 5       | TXD              | 15  | CANL                |
| 6       | V <sub>IO</sub>  | 16  | GND <sub>2</sub>    |
| 7       | GND <sub>1</sub> | 17  | CANH                |
| 8       | V <sub>CC</sub>  | 18  | S                   |
| 9       | GND <sub>1</sub> | 19  | V <sub>ISOIN</sub>  |
| 10      | GND <sub>1</sub> | 20  | GND <sub>2</sub>    |



| Device       | Package Type | Pin | MPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|--------------|--------------|-----|-----|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| TD541SCANH-S | DFN 10x13    | 20  | 300 | 180.0              | 24.4               | 13.52   | 10.52   | 3.5     | 16.0    | 24.0   | Q1            |

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