

# TD341S485S-FT DFN package isolated RS485 Transceiver

#### **Features**

- · Ultra-small, ultra-thin, chip scale DFN package
- · Compliant with TIA/EIA-485-A standard
- Integrated isolated 3.3V power
- I/O power supply range supports 3.3V and 5V microprocessors( Specific application

refer to "Recommendations 2")

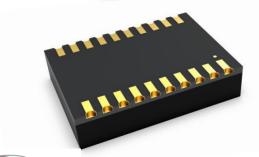
- · High isolation to 5000VDC
- Bus-Pin ESD protection up to 15kV(HBM)
- · Baud rate up to 20Mbps
- >25kV/us CMTI
- · Low communication delay
- Full-duplex
- 1/8 unit load—up to 256 nodes on a bus
- Bus fail-safe
- · Bus driver short circuit protection
- Industrial operating ambient temperature range: -40°C to +105°C
- · Meet AEC-Q100 standards
- Moisture Sensitivity Level (MSL) 3

#### **Applications**

- Industrial Automation
- Building Automation
- Smart Electricity Meter
- · Remote Signal Interaction, Transmission

#### Package







#### **Functional Description**

TD341S485S-FT is a full-duplex enhanced transceiver designed for RS-485 data bus networks, which is fully compliant with TIA/EIA-485-A standard and is suitable for data transmission of up to 20 Mbps. Their logic side supports 3.3V and 5V logic level conversion. Receivers have an exceptionally high input impedance, which places only 1/8 of the standard load on a shared bus and up to 256 transceivers.

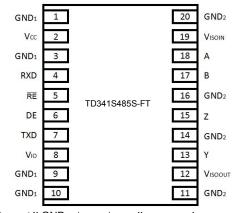
The reliability design of A, B, Z, Y pin is emphasized, including driver output over current protection and enhanced ESD design. The ESD protection level of A, B, Z, Y pin can be up to 15kV (Human Body Model).

#### **Contents**

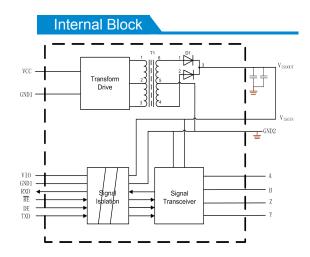
| 1 | Hom   | e                                |   |
|---|-------|----------------------------------|---|
|   | 1.1   | Feature and Package              |   |
|   | 1.2   | Applications                     | 1 |
|   | 1.3   | Functional Description           | 1 |
| 2 | Pin C | Connection and Description       | 2 |
| 3 | IC Re | elated Parameters                | 3 |
|   | 3.1   | Absolute Maximum Rating          | 3 |
|   | 3.2   | Recommended Operating Conditions | 3 |
|   | 3.3   | Electrical Characteristics       | 4 |
|   | 3.4   | Transmission Characteristics     | 5 |
|   | 3.5   | Physical Characteristics         | 5 |

| 4  | Char                         | acteristic Curve                  | 5  |  |  |
|----|------------------------------|-----------------------------------|----|--|--|
|    | 4.1                          | Typical Performance Curve         | .5 |  |  |
|    | 4.2                          | Parameter Measurement Information | 5  |  |  |
| 5  | Prod                         | uct working Description           | .6 |  |  |
| 6  | Appli                        | cation Circuit                    | .7 |  |  |
| 7  | Suggestions for Power Supply |                                   |    |  |  |
| 8  | Order Information            |                                   |    |  |  |
| 9  | Pack                         | age Information                   | 9  |  |  |
| 10 | 10 Tape & Reel Information10 |                                   |    |  |  |

## Pin Connection



Note: All  $\mathsf{GND}_1$  pins are internally connected. All  $\mathsf{GND}_2$  pins are internally connected.



## **Function Table**

| Letter | Description    |
|--------|----------------|
| Н      | High-Level     |
| L      | Low-Level      |
| X      | Unrelated      |
| Z      | High Impedance |

Table 1. Driver Function table

| TXD  | DE - | Ou | put |  |
|------|------|----|-----|--|
| IXD  |      | Y  | z   |  |
| Н    | Н    | Н  | L   |  |
| L    | Н    | L  | Н   |  |
| X    | L    | z  | z   |  |
| Open | Н    | Н  | L   |  |

Table 2. Receiver Function table

| Difference input<br>VID = (VA – VB) | RE | RXD         |
|-------------------------------------|----|-------------|
| -0.01 V ≤ VID                       | L  | Н           |
| -0.2 V < VID < -0.01 V              | L  | Uncertainty |
| V <sub>ID</sub> ≤ −0.2 V            | L  | L           |
| Х                                   | Н  | Н           |
| Open circuit                        | L  | Н           |
| Short circuit                       | L  | Н           |

## Pin Descriptions

| Pin Number | Pin Name            | Pin Functions  |  |  |
|------------|---------------------|--|--|--|
| 1          | GND₁                | Ground (Logic side).   |  |  |
| 2          | Vcc                 | Power supply. By using 0.1uF ceramic capacitance ground(GND <sub>1</sub> ).  |  |  |
| 3          | GND₁                | Ground (Logic side).   |  |  |
| 4          | RXD                 | Receiver output pin.   |  |  |
| 5          | RE                  | Receiver enable input. When $\overline{RE}$ is low, if $(A - B) \ge -10$ mV, then RXD = high. if $(A - B) \le -200$ mV, then RXD = low.                  |  |  |
| 6          | DE                  | Driver enable input. When DE is high, outputs are enabled. When DE is low, outputs are high impedance.  Drive DE low and RE high to enter shutdown mode. |  |  |
| 7          | TXD                 | Driver input pin.  |  |  |
| 8          | V <sub>IO</sub>     | Power supply of Logic side. By using 1uF ceramic capacitance ground(GND <sub>1</sub> ).  |  |  |
| 9          | GND₁                | Ground (Logic side).   |  |  |
| 10         | GND₁                | Ground (Logic side).   |  |  |
| 11         | GND <sub>2</sub>    | Ground (Bus Side).   |  |  |
| 12         | V <sub>ISOOUT</sub> | Insulation power output. By using 1uF Ceramic capacitance ground(GND <sub>2</sub> , pin11). The pin needs to be connected to pin19 in application.       |  |  |
| 13         | Y                   | Driver Noninverting Output.  |  |  |
| 14         | GND₂                | Ground (Bus Side).   |  |  |
| 15         | Z                   | Driver inverting Output.   |  |  |
| 16         | GND <sub>2</sub>    | Ground (Bus Side).   |  |  |
| 17         | В                   | Receiver Inverting Input.  |  |  |
| 18         | Α                   | Receiver Noninverting Input.   |  |  |
| 19         | V <sub>ISOIN</sub>  | Insulation power input. By using 0.1uF ceramic capacitance ground(GND <sub>2</sub> , pin20). The pin needs to be connected to pin12 in application.      |  |  |
| 20         | GND <sub>2</sub>    | Ground (Bus Side).   |  |  |

## **Absolute Maximum Ratings**

General test conditions: Free-air, normal operating temperature range (Unless otherwise specified).

| Parameters                               | Unit   |
|--|--|
| Supply voltage ( Vcc )                   | -0.3V to +3.5V   |
| V <sub>IO</sub> Input Voltag             | -0.3V to+6V  |
| A, B, Z, Y Bus voltage                   | -8V to+13V   |
| Digital Input Voltage (DE, RE, TXD, RXD) | -0.3V to+6V  |
| Operating Temperature Range              | −40°C to +105°C  |
| Storage Temperature Range                | −50°C to +125°C  |
| Reflow Soldering Temperature             | Peak temp. ≤250°C, maximum duration ≤60s at 217°C. Please also refer to IPC/JEDEC J-STD-020D. 3. |

Important: Exposure to absolute maximum rated conditions for an extended period may severely affect the device reliability, and stress levels exceeding the "Absolute Maximum Ratings" may result in permanent damage.

## **Recommended Operating Conditions**

| Symbol          | Recommended O               | Min.                                  | Тур.       | Max. | Unit            |      |
|-----------------|-----------------------------|---------------------------------------|------------|------|-----------------|------|
| Vcc             | Suppl                       | y voltage                             | 3.15       | 3    | 3.45            |      |
| V <sub>IO</sub> | Suppl                       | y voltage                             | 2.375      | 3.3  | 5.5             |      |
| Vı              | Voltage at any bus terminal | (differential or common mode)         | -7         |      | 12              | V    |
| V <sub>IH</sub> | High-level input vo         | High-level input voltage(TXD, DE, RE) |            |      | V <sub>IO</sub> |      |
| V <sub>IL</sub> | Low-level input vo          | ltage(TXD, DE, RE)                    | 0          |      | 0.8             |      |
|                 | Outrout surrout             | Driver                                | Driver -60 |      | 60              | A    |
| los             | Output current Receiver     |                                       | -8         |      | 8               | mA   |
| R <sub>IN</sub> | Differential out            | Differential output load resistance   |            | 60   |                 | Ω    |
| T <sub>A</sub>  | Operating temperature range |                                       | -40        |      | 105             | °C   |
| -               | Signa                       | aling rate                            |            |      | 20              | Mbps |

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## Electrical Characteristics

| Symbol                 | Parameter   | Conditions   |  | Min.                   | Тур.                  | Max. | Unit  |
|------------------------|---|--|--|------------------------|-----------------------|------|-------|
| Driver                 |   |  |  |                        |                       |      |       |
|                        |   | No load  |  | 3.0                    |                       |      | V     |
| $ V_{\text{OD}} $      | Differential driver output                                | R <sub>L</sub> = 54Ω   | , Figure 7                                     | 1.5                    | 2.0                   |      | .,,   |
|                        |   | R <sub>L</sub> = 1000  | Σ, Figure 7                                    | 2.0                    |                       |      | V     |
| $\Delta V_{\text{OD}}$ | Δ V <sub>OD</sub>   for complementary output states       | R <sub>L</sub> = 54Ω   | , Figure 7                                     |                        |                       | ±0.2 | V     |
| Voc                    | Common-Mode output voltage                                | Figu   | ıre 6  | 1                      |                       | 3    | V     |
| $\Delta Voc(ss)$       | Δ V <sub>OC</sub>   for complementary output states       | Figu   | ıre 6  | -0.1                   |                       | 0.1  | V     |
| los                    | Output short-circuit current                              | -7V ≤ V <sub>A</sub> o   | or V <sub>B</sub> ≤ 12V                        |                        | ±110                  | ±250 | mA    |
| Receiver               |   |  |  |                        |                       |      |       |
| VIT(+)                 | Positive differential input threshold voltage             | -7 V ≤ V <sub>A</sub> o  | r V <sub>B</sub> ≤ +12 V                       |                        |                       | -10  | mV    |
| VIT(-)                 | Negative differential input threshold voltage             | -7 V ≤ V <sub>A</sub> o  | r V <sub>B</sub> ≤ +12 V                       | -200                   |                       |      | mV    |
| Vhys                   | Hysteresis voltage (V <sub>IT+</sub> – V <sub>IT-</sub> ) | -7 V ≤ V <sub>A</sub> o  | r V <sub>B</sub> ≤ +12 V                       |                        | 20                    |      | mV    |
| RID                    | Differential input resistance(A, B)                       | -7 V ≤ V <sub>A</sub> o  | r V <sub>B</sub> ≤ +12 V                       | 96                     |                       |      | kΩ    |
| I.                     | Input current (A, B)                                      | DE=0, RE =0,   | V <sub>OUT</sub> = 12V                         |                        | 190                   | 250  | uA    |
| lı                     |   | iii iiiput cuireiit (A, B)                                       | V <sub>CC</sub> =0 or 3.3V                     | V <sub>OUT</sub> = -7V | -200                  | -110 |       |
| Vон                    | RXD output high voltage                                   | $I_{OUT}$ = 20 $\mu$ A, $\gamma$                                 | $V_{A} - V_{B} = 0.2 \text{ V}$                | V <sub>IO</sub> - 0.1  |                       |      | V     |
| VOH                    | NAD output high voltage                                   | I <sub>OUT</sub> = 4 mA, V <sub>A</sub> - V <sub>B</sub> = 0.2 V |  | V <sub>IO</sub> - 0.4  | V <sub>IO</sub> - 0.2 |      | V     |
| Vol                    | RXD output low voltage                                    | $I_{OUT} = -20 \mu A, V_A - V_B = -0.2 V$                        |  |                        |                       | 0.1  | V     |
| VOL                    | NAD output low voltage                                    | $I_{OUT} = -4 \text{ mA}, V$                                     | $V_A - V_B = -0.2 \text{ V}$                   |                        |                       | 0.4  | V     |
| Power supply           | and safeguard characteristic                              |  |  |                        |                       |      |       |
| Icc                    | Supply current  | DE = RE = 0V   |  |                        | 18                    | 40   | mA    |
| 1                      | Morking ourrent   | Between Y,   | Z 100Ω load                                    |                        | 95                    | 125  | mA    |
| lcc                    | Working current   | Between Y,   | Z 54Ω load                                     |                        | 105                   | 135  | mA    |
| ESD                    | НВМ   | A, B, Y, 2   | Z to GND                                       |                        |                       | ±15  | kV    |
| ESD                    | ным   | Othe   | er pin   |                        |                       | ±2   | kV    |
| EFT                    | IEC61000-4-4  | A, B, Y, Z and GND   |  |                        |                       | ±2   | kV    |
| SURGE                  | IEC61000-4-5  | A, B, Y, Z and GND(Common Mode)                                  |  |                        |                       | ±2   | kV    |
|                        | Insulate voltage  |  |  |                        |                       | 5000 | VDC   |
| VI-O                   | Insulate impedance  |  |  | 1                      |                       |      | GΩ    |
|                        | Insulate capacitance                                      |  |  |                        | 3                     |      | pF    |
| CMTI                   | Common mode transient immunity                            |  | O V, V <sub>CM</sub> = 1 kV,<br>nitude = 800 V | 25                     |                       |      | kV/us |

## Transmission Characteristics

| Symbol                              | Parameter  | Conditions                                 | Min. | Тур. | Max. | Unit |
|-------------------------------------|--|--|------|------|------|------|
| -                                   | Maximum data rate  | Duty 40% ~ 60%                             |      |      | 20   | Mbps |
| T <sub>PHL</sub> , T <sub>PLH</sub> | Driver propagation delay                                 |  |      | 25   | 90   | ns   |
| T <sub>PHL</sub> -T <sub>PLH</sub>  | Driver skew (  TPHL - TPLH  )                            | $R_L = 54\Omega$ , $C_L = 50$ pF, Figure 8 |      |      | 15   | ns   |
| T <sub>R</sub> , T <sub>F</sub>     | Driver rise/fall time                                    |  |      |      | 60   | ns   |
| T <sub>PHL</sub> , T <sub>PLH</sub> | Receiver propagation delay                               | C = 15pF Figure 0                          |      | 60   | 150  | ns   |
| T <sub>PHL</sub> -T <sub>PLH</sub>  | Receiver skew (  T <sub>PLH</sub> - T <sub>PHL</sub>   ) | C <sub>L</sub> = 15pF Figure 9             |      | 10   | 20   | ns   |
| $T_R$ , $T_F$                       | Receiver rise/fall time                                  | C <sub>L</sub> = 15pF Figure 9             |      | 25   |      | ns   |

| Parameters | Value      | Unit |
|------------|------------|------|
| Weight     | 1.0(Typ. ) | g    |

## **Typical Performance Curves**

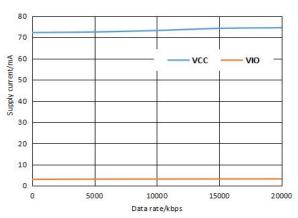


Figure 1. Supply current vs. Data rate 100 tPLH 90 80 70 Receiver Delay/ns 60 50 40 30 20 10 0 -40 18 47 76 105 Operating temperature/°C

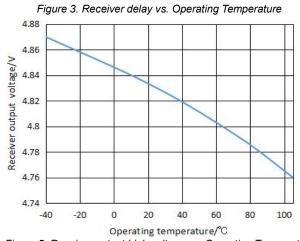
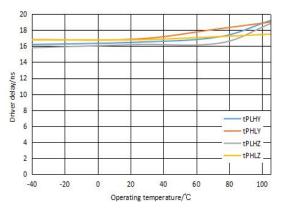


Figure 5. Receiver output high voltage vs. Operating Temperature



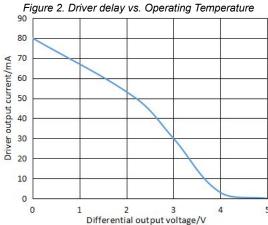


Figure 4. Driver output current vs. Differential output voltage

Note: Testing the condition burden capacitance including test to stretch forward and testing fixture parasitic capacitance. Testing semaphore upswing and drop to follow < 6ns, frequency = 100kHz, duty = 50%. resistance ZO =  $54\Omega$ .

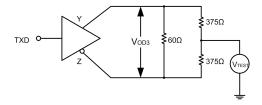


Figure 6. Driver test circuit, VOD with common-mode loading

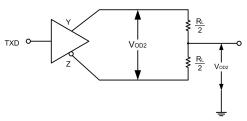
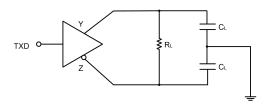


Figure 7. Driver test circuit



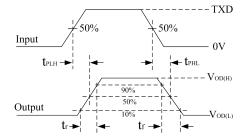
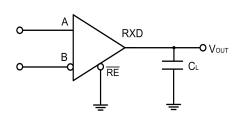


Figure 8. Drive propagation delay test circuit and wave forms



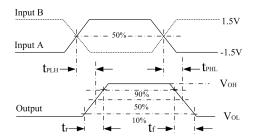


Figure 9. Receiver propagation delay test circuit and wave forms

#### **Detailed Description**

TD341S485S-FT is a full-duplex enhanced RS485 isolated transceiver with isolated power supply. In addition to an isolated power supply, each transceiver contains a drive and a receiver. The transceiver has a standby bus failure protection function to ensure that the receiver output is high when the receiver input is open, short, or when the bus is idle. TD341S485S-FT adopts 3.3VDC power supply. The whole machine can monitor the overall working state of the module and limit the output high current, so as to prevent the bus overload or short circuit from causing non-recoverable damage to the transceiver.

Receiver input filter: TD341S485S-FT receiver integrated high performance input filter, the filter can greatly enhance the receiver's noise suppression ability to high speed differential signal. Therefore, the transmission delay of the receiver is also caused by this reason.

Bus failure protection: In general, when -200mV < A - B < -10mV, the bus receiver will be in an uncertainty state. This phenomenon occurs when the bus is idle. Bus failure protection ensures that the receiver outputs a high level when the receiver input is open, short, or when the bus access port matches the resistance. TD341S485S-FT receiver threshold voltage is relatively accurate, and the threshold voltage to the reference ground has a margin of at least 10mV, which can ensure that even if the bus differential voltage is 0V, the receiver output level is high, and meets the requirements of EIA/TIA-485 standard ±200mV.

The bus load capacity (256 point): standard RS485 receiver input impedance is defined as  $12 \text{ k}\Omega$  (unit load). A standard RS485 driver can drive at least 32 load units. TD341S485S-FT bus receiver designed by 1/8 unit load, the input impedance is greater than 96 k $\Omega$ . As a result, the bus allows access to more transceivers (up to 256). TD341S485S-FT can also be mixed with the standard RS485 transceiver with 32 unit loads (cumulative receiver load cannot exceed 32 units).

Low power SHUTDOWN mode: When high level is input and low power is input, the transceiver enters SHUTDOWN mode. When the transceiver enters off mode, its overall standby power consumption decreases, DE can be short-connected and controlled by the same I/O. If the high level of  $\overline{RE}$  is input and the holding time of  $\overline{RE}$ , DE low level is less than 50ns, the transceiver cannot enter the off mode. If the holding time can be maintained at least 600ns, the transceiver will reliably enter the off mode.

Drive output protection: TD341S485S-FT internal integrated drive short circuit (or overcurrent) protection module. In case of bus error or driver short circuit, the module can limit the output current of the driver within a certain limit.

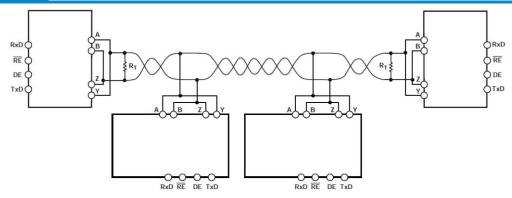


Figure 10. Typical Application Circuit (Half-Duplex Network Topology)

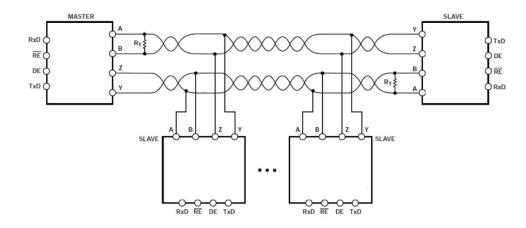


Figure 11. Typical Application Circuit (Full-Duplex Network Topology)

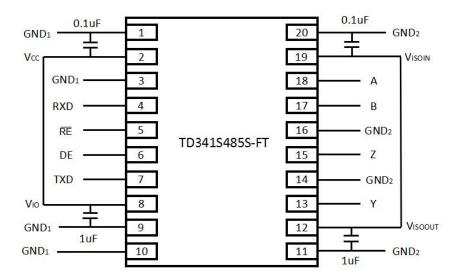


Figure 12. Typical Application of PCB layout

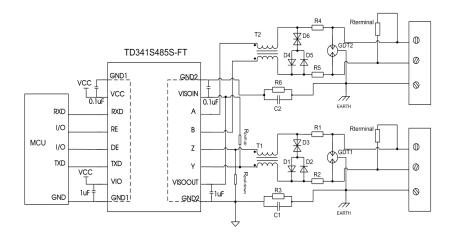


Figure 13. Port protection circuit for harsh environments

#### Recommended components and values:

| Component | Recommended part, value | Component             | Recommended part, value |
|-----------|-------------------------|-----------------------|-------------------------|
| R3,R6     | 1ΜΩ                     | R1,R2,R4,R5           | 2.7Ω/2W                 |
| C1,C2     | 1nF, 2kV                | D1,D2,D4,D5           | 1N4007                  |
| T1,T2     | ACM2520-301-2P          | D3,D6                 | SMBJ8.5CA               |
| GDT1,GDT2 | B3D090L                 | R <sub>terminal</sub> | 120 Ω                   |

As the modules internal A / B / Z / Y lines come with its own ESD protection, which generally satisfy most application environments without the need for additional ESD protection devices. For harsh and noisy application environments such as motors, high voltage/current switches, lightning and similar however, we recommended that the user protects the module's A / B / Z / Y lines with additional measures and external components such as TVS tube, common mode inductors, Gas discharge tube, shielded twisted pair of wires with the same single network Earth point. Figure 13 shows our recommended circuit diagram for such type of applications with components and values given in the table above. This recommendation is for reference only and may have to be adapted accordingly with appropriate component values in order to match the actual situation and application.

- Note 1: Select the R<sub>terminal</sub> according to the actual application.
- Note 2: When using the port protection circuit, you need to slow down the baud rate.

### Recommendations

- ① Power isolation V<sub>ISOOUT</sub> need through a series of capacitors connected to the output pin V<sub>ISOIN</sub>, in addition to the mentioned in ⑤ of the pull up and down function, the power supply is not recommended for other purposes, otherwise it may cause the bus voltage did not meet the requirements of communication, causes the communication failure.
- ②  $V_{IO}$  pin decide the output level of RXD pin. Normally,  $V_{IO}$  pin need to connected to the  $V_{cc}$  pin to support 3.3V microprocessors.  $V_{IO}$  pin need to disconnect to the  $V_{cc}$  pin and need a 5V power supply separately to support 5V microprocessors if necessary.
- ③ DE and TXD contains a 10kΩ pull up resistor each,  $\overline{RE}$  contains a 10kΩ pull down resistor.
- ④ DE, RE, TXD pin is always not allow to set to open drain output state connect the controller, otherwise it will lead to uncertain consequences.
- (§) To maintain bus idle stability, we need at least one node will pull up Y to  $V_{ISOIN}$  and drop down Z to GND2 on the bus. Overall network at the same time pull up and drop down resistors of the parallel value must around  $380\Omega$  to  $420\Omega(0.2W)$

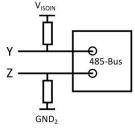


Figure 14. Pull up and drop down resistance connect

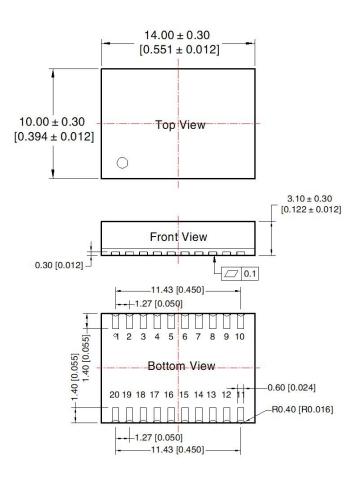
- 6 Hot-swap is not supported.
- ② If the external input of TXD is insufficient, the pull-up resistor should be added according to the situation.

® Refer to IPC 7093 for the welding process design of this product. For detailed operation guidance, please refer to Hot Air Gun Welding Operation Instruction for DFN Package Product or Welding Operation Instruction for DFN Package Product.

#### **Ordering Characteristics**

| Part number Package |     | Number of pins | Product marking | Tape & Reel |  |  |
|---------------------|-----|----------------|-----------------|-------------|--|--|
| TD341S485S-FT       | DFN | 20             | TD341S485S-FT   | 300/REEL    |  |  |

#### Package Information

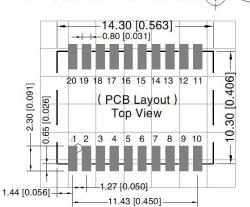


Note:

Unit: mm[inch]

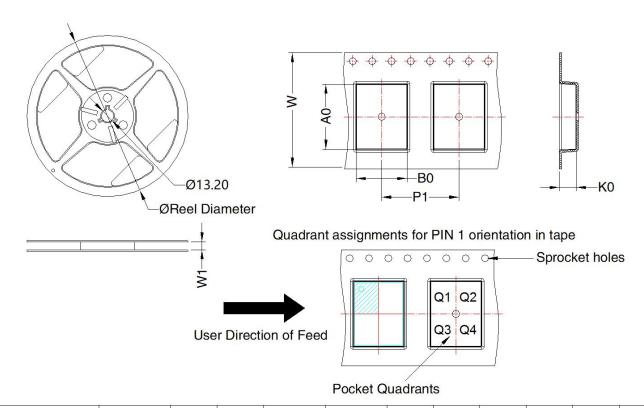
General tolerances:  $\pm 0.10[\pm 0.004]$ 

## THIRD ANGLE PROJECTION



Note: Grid 2.54\*2.54mm

| Pin-Out |                  |     |         |  |  |  |  |  |
|---------|------------------|-----|---------|--|--|--|--|--|
| Pin     | Mark             | Pin | Mark    |  |  |  |  |  |
| 1       | GND₁             | 11  | GND₂    |  |  |  |  |  |
| 2       | Vcc              | 12  | Visoout |  |  |  |  |  |
| 3       | GND <sub>1</sub> | 13  | Υ       |  |  |  |  |  |
| 4       | RXD              | 14  | GND₂    |  |  |  |  |  |
| 5       | RE               | 15  | Z       |  |  |  |  |  |
| 6       | DE               | 16  | GND₂    |  |  |  |  |  |
| 7       | TXD              | 17  | В       |  |  |  |  |  |
| 8       | V <sub>IO</sub>  | 18  | Α       |  |  |  |  |  |
| 9       | GND₁             | 19  | Visoin  |  |  |  |  |  |
| 10      | GND₁             | 20  | GND₂    |  |  |  |  |  |



| Device        | Package<br>Type | Pin | MPQ | Reel<br>Diameter<br>(mm) | Reel<br>Width<br>W1 (mm) | A0<br>(mm) | B0<br>(mm) | K0<br>(mm) | P1<br>(mm) | W<br>(mm) | Pin1<br>Quadrant |
|---------------|-----------------|-----|-----|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| TD341S485S-FT | DFN 10x14       | 20  | 300 | 180.0                    | 24.4                     | 14.52      | 10.52      | 3.5        | 16.0       | 24.0      | Q1               |

## MORNSUN Guangzhou Science & Technology Co., Ltd.

Address: No. 5, Kehui St. 1, Kehui Development Center, Science Ave., Guangzhou Science City, Huangpu District, Guangzhou, P. R. China Tel: 86-20-38601850 Fax: 86-20-38601272 E-mail: info@mornsun.cn www.mornsun-power.com